Workshop Talk on Approximate Inference of Influences by Bounds on Confounding

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- 1. Motivating example
- 2. General problem description
- 3. Outline of our approach
- 4. Part 1 of our approach: Formalizing dependence versus effect

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- 5. Part 2 of our approach: Prototypical application scenarios
- 6. Conclusion

Imagine you observe

Whenever a patient takes a certain drug, he/she recovers the same day.

Intuitive conclusion

Drug is effective because in this scenario no confounder can be that strong (deterministic).

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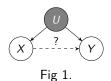
Later we will see ...

... how this intuition can be formalized.

General problem description

Given

- The joint distribution P(X, Y), induced by a causal model with potential hidden confounder U and causal DAG as in Fig. 1.
- Some form of additional knowledge which implies "bounds on confounding".



Goal

Estimate post-interventional distribution P(Y|do X=x) [Pearl, 2000] or related quantities such as the effect of treatment on the treated (ETT) [Pearl, 2000] or the causal strength from X to Y, denoted by $\mathfrak{C}_{X\to Y}$ [Janzing et al., 2013].

Outline of our approach

Part 1: Formalizing dependence versus effect

Our approach consists of two parts.

In part 1, we propose various formalizations of the following intuitive notions:

- Observed dependence: the statistical dependence between X and Y (i.e. based on P(X, Y)).
- ► **Back-door dependence:** the "spurious association" [Pearl, 2000] between X and Y due to U.
- **Causal effect:** what happens to Y upon intervening on X.

Outline of our approach

Part 1: Formalizing dependence versus effect (ctd.)

For all formalizations one can derive inequalities of the form:

$$\left[\begin{array}{c} \mathsf{back-door} \\ \mathsf{dependence} \end{array} \right] \geq \mathrm{d} \left(\left[\begin{array}{c} \mathsf{observed} \\ \mathsf{dependence} \end{array} \right], \left[\begin{array}{c} \mathsf{causal} \\ \mathsf{effect} \end{array} \right] \right).$$

 $d(\cdot, \cdot)$ either stands for " $\cdot - \cdot$ " (the usual difference) or " $D[\cdot \| \cdot]$ " (the KL divergence).

In the former case we can also write:

$$\left[\begin{array}{c} \mathsf{causal} \\ \mathsf{effect} \end{array} \right] \geq \left[\begin{array}{c} \mathsf{observed} \\ \mathsf{dependence} \end{array} \right] - \left[\begin{array}{c} \mathsf{back-door} \\ \mathsf{dependence} \end{array} \right]$$

NB: For some formalizations we can even prove equalities, instead of inequalities.

Part 2: Prototypical application scenarios

For the inequalities from part 1 to be applicable, we need bounds on the back-door dependence.

Therfore in **part 2** we discuss several prototypical scenarios which imply such bounds, and apply part 1.

Remark: how to find such scenarios?

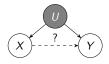
- Main difficulty: Find conditions which are weak enough to be met in realistic scenarios, but strong enough to imply bounds on back-door dependence.
- General intuition: strength of back-door dependence = deviation from randomized experiment.

Part 1: Formalizing dependence versus effect Estimating the causal effect p(Y|do X=x)

Here we formalize the intuitive notions by:

- observed dependence: p(Y|X=x),
- ▶ back-door dependence: min{𝔅_{U→X}, 𝔅_{U→Y}}, I(X : U),

• causal effect:
$$p(Y|do X=x)$$
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Theorem

 $\mathrm{D}[p(Y|X) \parallel p(Y|\mathrm{do} X)] \leq \min\{\mathfrak{C}_{U \to X}, \mathfrak{C}_{U \to Y}\} \leq \mathrm{I}(X : U).$

Part 1: Formalizing dependence versus effect Estimating the causal strength $\mathfrak{C}_{X \to Y}$

Here we formalize the intuitive notions by:

- observed dependence: I(X : Y),
- ▶ back-door dependence: $\mathfrak{C}_{U \to X}$,
- causal effect: $\mathfrak{C}_{X \to Y}$.

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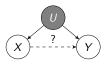
Theorem

$$\mathfrak{C}_{U\to X} \geq \mathrm{I}(X:Y) - \mathfrak{C}_{X\to Y}.$$

Part 1: Formalizing dependence versus effect Estimating the differential ETT from X to Y

Here we formalize the intuitive notions by:

- observed dependence: $d_x \mathbb{E}[Y|X=x]$,
- ► back-door dependence: $\partial_2 \mathbb{E}[Y_{\text{do } X=x} | X = x]$ (∂_i is the partial derivative),
- ► causal effect: ∂₁E[Y_{do X=x}|X = x], NB: this is a differential version of the effect of treatment on the treated (ETT), E[Y_{do X=x'}|X=x'] - E[Y_{do X=x}|X=x'].



Theorem

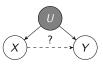
For all x we have

$$\partial_2 \mathbb{E}[Y_{\mathrm{do}\,X=x}|X=x] = \mathrm{d}_x \mathbb{E}[Y|X=x] - \partial_1 \mathbb{E}[Y_{\mathrm{do}\,X=x}|X=x].$$

Part 2: Prototypical application scenarios Formalizing the intuition in the motivating example

Formalizing the drug efficacy scenario

► Let X be weekday of intake, Y be weekday of recovery.



- Recall the observation: $p(y|x) = \delta_{yx}$ (Kronecker delta).
- ► Recall the intuition: U cannot fully determine X.
 ~→ I(U : X) < H(X) (bound on back-door dependence).</p>

Results from part 1 imply

$$\exists x, x' \text{ such that } p(Y | \text{do} X = x) \neq p(Y | \text{do} X = x').$$

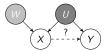
→ Drug is effective.

Part 2: Prototypical application scenarios Estimating the effect of advertisement letters

Scenario: mail order company, efficacy of ad. letters

- ► X: advertisement letter was sent out to a person.
- > *Y*: ordering behavior of this person afterwards.
- ► W: letter was sent out based on guidelines U or randomly. We do not observe W, but know p(W).

$$\blacktriangleright X := \begin{cases} f(U, N_X), & \text{if } W = 1, \\ f'(N_X), & \text{if } W = 0. \end{cases}$$



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Results from part 1 imply

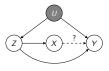
$$\mathfrak{C}_{X \to Y} \ge I(X:Y) - H(X)p(W=1).$$

Part 2: Prototypical application scenarios Variant of the regression discontinuity design (RDD)

NB: RDD [Thistlewaite et al., 1960] uses discontinuity in $Z \rightarrow X$.

Scenario: "differential version" of the RDD

- Observe Z, X, Y, know causal structure.
- X := f(Z) differentiable, invertible. g := f⁻¹.



Results from part 1 imply $\overbrace{\partial_2 \mathbb{E}[Y_{\text{do} X=x} | Z=g(x)]}^{(*)} g'(x) = d_x \mathbb{E}[Y|X=x] - \partial_1 \mathbb{E}[Y_{\text{do} X=x} | X=x].$

Therefore

If $|f'(x_0)|$ big $(|g'(f(x_0))|$ small) and (*) bounded, then the above equation helps to estimate the causal effect.

- Presented various formalizations of the intuitive notions of observed dependence, back-door dependence and causal effect.
- Always: back-door dependence bounds deviation between observed dependence and causal effect.
- Discussed prototypical scenarios which allow to bound the back-door dependence and thus to apply the above bound.

• **Open problem:** finding real applications.

Paper underlying this talk: P. Geiger, D. Janzing, and B. Schölkopf: Estimating Causal Effects by Bounding Confounding. UAI, 2014.

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